



# GUJARAT TECHNOLOGICAL UNIVERSITY

**Master of Engineering**  
**Subject Code: 3720219**  
**Semester – II**  
**Subject Name: Computer Vision**

**Type of course: Elective**

**Prerequisite:** Linear Algebra, Vector Calculus, Data Structures and Programming.

**Rationale:**

- Be familiar with both the theoretical and practical aspects of computing with images.
- Have described the foundation of image formation, measurement, and analysis.
- Understand the geometric relationships between 2D images and the 3D world.
- Grasp the principles of state-of-the-art deep neural networks.

**Teaching and Examination Scheme:**

Teaching Scheme			Credits C	Examination Marks				Total Marks
L	T	P		Theory Marks		Practical Marks		
			ESE (E)	PA (M)	ESE (V)	PA (I)		
3	0	2	4	70	30	30	20	150

**Content:**

Sr. No.	Content	Total Hrs	% Weightage
1	Overview, computer imaging systems, lenses, Image formation and sensing, Image analysis, pre-processing and Binary image analysis.	8	16%
2	Edge detection, Edge detection performance, Hough transform, corner detection	9	19%
3	Segmentation, Morphological filtering, Fourier transform	9	19%
4	Feature extraction, shape, histogram, color, spectral, texture, using CV IP tools, Feature analysis, feature vectors, distance /similarity measures, data preprocessing	9	19%
5	Pattern Analysis: Clustering: K-Means, K-Medoids, Mixture of Gaussians Classification: Discriminant Function, Supervised, Un-supervised, Semi-supervised Classifiers: Bayes, KNN, ANN models; Dimensionality Reduction: PCA, LDA, ICA, and Non-parametric methods.	9	19%
6	Recent trends in Activity Recognition, computational photography, Biometrics.	4	8%
	<b>Total</b>	<b>48</b>	<b>100%</b>



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## Reference Books:

1. Computer Vision: Algorithms and Applications by Richard Szeliski.
2. Computer Vision – A modern approach, by D.Forsyth and J.Ponce, Prentice Hall Robot Vision, by B. K. P. Horn, McGraw-Hill.
3. Deep Learning, by Goodfellow, Bengio, and Courville.
4. Dictionary of Computer Vision and Image Processing, by Fisher et al.
5. Three-Dimensional Computer Vision, by Olivier Faugeras, The MIT Press.

## Course Outcomes:

At the end of the module the student will be able to:

Sr. No.	CO statement	Marks % weightage
CO-1	Identify basic concepts, terminology, theories, models and methods in the field of computer vision.	20%
CO-2	Describe basic methods of computer vision related to multi-scale representation, edge detection and detection of other primitives, stereo, motion and object recognition.	35%
CO-3	Developed the practical skills necessary to build computer vision applications.	30%
CO-4	To have gained exposure to object and scene recognition and categorization from images.	15%

## List of Experiments:

1. To perform variants of linear filter on an image.
2. To perform median filter on an image.
3. To perform all morphological filter operations on the image.
4. To perform edge detection on an image using Sobel, Prewitt, Roberts and Canny Method.
5. To perform Hough transform on an image.
6. Generate histogram and perform histogram equalization of an image.
7. To perform clustering using any technique on the image.
8. To perform various pattern classification and analysis techniques on images.
9. To perform various pattern clustering and analysis techniques on images.

**List of Open Source Software/learning website:** Open CV, Python